

EntréPad AES1610 Slide Sensor Data Sheet

Features and Benefits

- TruePrint® and TrueMatch® Technology
 - Best Ability To Acquire (ATA)
- ✓ TrueNav® Cursor and Menu Navigation Technology
 - Quickly scroll through menus, lists and documents
- ✓ High Definition 128 x 8 Pixel Array
 - o 6.5mm x 0.40mm
 - o 500 pixels per inch
- ✓ Ultra Small Package
 - 40 Ball Grid Array (BGA) eXtendaBall Packages
 - 12mm X 5mm X 1.96mm (thick)
 - o 12mm X 5mm X 1.34mm (thin)
 - Perfect for notebooks, UMPCs, PC desktop peripherals, and small handheld devices
 - RoHS Compliant

✓ Serial Flash Interface

 Secure matcher and template storage during pre-boot authentication (PBA)

- USB Operating Voltage Range
 3.0V to 3.6V single supply
- ✓ 0°C to +70°C Operating Temperature Range
- ✓ USB 2.0 Full Speed Interface
 - Suspend and remote wakeup
 - Full support for C3 Selective Suspend mode
- Multiple Frequency Operation with Crystal, Resonator, or with external clock input
- ✓ Ultra-Hard Wearing Surface Coating
 - Scratch and impact resistant
 - > 10 Million rubs w/o
 - degradation
- ✓ IEC 61000-4-2 Level 4 ESD Immunity (+/- 15KV)
- Built-in low power Finger Detection
 w/ remote wakeup capability
- Multiple battery-friendly operating modes @ 3.3V
 - Imaging @ 25 37 mA typical depending upon slide speed selection
 - Navigation / Graphical Cursor Control mode @ 10.5 mA typical.

1 Introducing the EntréPad AES1610 Slide Sensor

1.1 Operational Description

The AES1610 combines a USB2.0 full speed interface with compact size and low voltage low power operation. The USB interface features low-power suspend and remote wakeup capability. The AES1610 also includes a private Serial Flash SPI interface, providing simplified integration into PC pre-boot authentication while improving PC serviceability and customer privacy.

The AES1610 fingerprint sensor is a flexible subsurface fingerprint imaging device capable of performing many different functions at the touch of a finger. The primary functions of the sensor are to accurately detect and read an individuals fingerprint and finger motions under all conditions putting the power of touch to work for you. AuthenTec's TruePrint Technology and proprietary pattern-based matching algorithms deliver the industry's best Ability-To-Enroll (ATE) >>99%, False Acceptance Rate (FAR) <1:100,000, and lowest False Rejection Rate (FRR) < 1:500. The low FRR ensures that your customers will be able to easily authenticate themselves with the sensor without having to re-slide their finger due to unnecessary nuisance rejects while at the same time maintaining a high-level of security. The on-chip navigation timing and image optimization functions provide for high resolution motion calculation for all types of finger motions.

The TruePrint image pixel array of the AES1610 sensor is composed of 8 rows of 128 pixels (columns) at a pixel density of 500 pixels per inch. This highly advanced imaging system provides unparalleled accuracy and gives the AES1610 the outstanding biometric performance. The AES1610 features a full image frame buffer, further enhancing in-system performance. The slide speed of the device is selectable and ranges from 20cm/s to 50cm/s depending upon your requirements.

During an imaging event, the RF TruePrint Signal is conducted via the drive ring to the users' finger. The TruePrint Signal is then conducted through and modulated by the "live layer" of the finger where the true fingerprint originates. The imaging array measures the TruePrint signal, the strength of which corresponds to either a ridge or valley region. The sensing element of each pixel is an RF sense-amplifier, which picks up the TruePrint (high frequency AC) signal.

The AES1610 makes decision concerning the presence of a finger based on histograms created during imaging cycles. If the host places the sensor in suspend with the USB Remote Wakeup feature enabled, the AES1610 will automatically enter the continuous finger detect mode. The host can program all relevant registers of the sensor prior to placing it in suspend so that the sensor is setup to properly image or navigate when a finger is found. The host will program the sensor to ensure that the sensor will not consume more than 500uA while in suspend.

2 DC ELECTRICAL CHARACTERISTICS

2.1 Absolute Maximum Ratings

An absolute maximum rating is the maximum value guaranteed by the AuthenTec. The use of a product in violation of these ratings can result in significant loss of device reliability or cause damage to the sensor.

| Symbol | Parameter | Min. | Max. | Units |
|------------------------|---|------|----------------------|-------|
| V _{DD} | Supply Voltage | -0.5 | 4.3 | V |
| VI | Input Voltage | -0.5 | V _{DD} +0.5 | V |
| Vo | Output Voltage | -0.5 | V _{DD} +0.5 | V |
| I _{IK} | Input Clamp Current VI < V _{SS} of VI > V _{DD} | | ±20 | mA |
| Ι _{ΟΚ} | Output Clamp Current $V_O < V_{SS}$ of $V_O > V_{DD}$ | | ±20 | mA |
| T _{STG} | Storage Temperature | -65 | 150 | °C |
| Latch-Up | Latch-Up Immunity | ±100 | | mA |
| ESD _{PIN} | Pin-level ESD Immunity JESD22 Method A114-B | -2 | +2 | KV |
| ESD _{PACKAGE} | Package-level ESD Immunity IEC61000-4-2 Level 4 Air Discharge method using AuthenTec approved reference design | -15 | +15 | KV |
| T _{SOL} | Maximum Soldering Temperature (MSL=3) | | +260 | °C |

Absolute Maximum Ratings

2.2 Recommended Operating Conditions

| Symbol | Parameter | Min. | Тур | Max. | Units |
|----------------------|----------------------------------|---------------|-----|-----------------|---------|
| V _{DD} | Power Supply Voltage | 3.0 | - | 3.6 | V |
| V _{DDACp-p} | Power Supply Ripple peak to peak | -50 | | +50 | mV |
| VI | Input Voltage | 0 | | V_{DD} | V |
| Vo | Output Voltage | 0 | | V_{DD} | V |
| V _{IH} | High Level Input Voltage | $70\% V_{DD}$ | | V _{DD} | V |
| VIL | Low Level Input Voltage | 0 | | $30\% V_{DD}$ | V |
| tt | Digital Input Transition (Rise | 3 | | 10 | nS |
| | and Fall) Time | | | | |
| T _A | Ambient operating | 0 | | 70* | • O° |
| | temperature | | | | |

Recommended Operating Conditions

*Advisory

The AES1610 remains fully operational at temperatures that are high enough to be uncomfortable for the user.

For reasons of safety and protection, AuthenTec reference designs include circuitry that serves to manage the junction temperature by controlling the supply current. If the hardware developer elects not to use the AuthenTec-provided control circuit design, it will then be essential that an equivalent design be developed and implemented.

2.3 DC Characteristics @ Recommended Operating Conditions

| Symbol | Parameter | Conditions | Min. | Тур | Max. | Units |
|---------------------|--|--------------|-------------------|------|------|-------|
| V _{OH} | High Level Output Voltage | IOH=2mA | V _{dd} - | | | V |
| | | | 0.3 | | | |
| V _{OL} | Low Level Output Voltage | IOL=2mA | | | 0.3 | V |
| IIL | Low Level Input Current | VI=VIL(min.) | | | ±1 | μA |
| I _{IH} | High Level Input Current | VI=VIH(max. | | | ±1 | μA |
| I _{OZ} | High Impedance State Output Current | | | | ±20 | μA |
| Power S | upply Currents | | | | | |
| I _{DDQ} | Imaging mode @ 20cm/s | Vdd=3.3V | | 31 | | mA |
| I _{DDQ} | Imaging mode @ 30cm/s | Vdd=3.3V | | 37 | | mA |
| I _{DDQ} | Navigation | Vdd=3.3V | | 10.5 | | mA |
| I _{DDQ} | Suspend Mode C3-State Selective Suspend | Vdd=3.3V | | | 400 | uA |
| I _{DDQ} | Idle Mode | Vdd=3.3V | | 4.4 | | mA |
| I _{DDPeak} | Peak Imaging Current | Vdd=3.3V | | | 89 | mA |

Unless otherwise specified, $V_1 = V_{DD}$ or V_{SS} , $T_{Ambient} = 25^{\circ}C$

DC Characteristics

All I_{DDQ} Currents measured RMS using standard AuthenTec software and drivers. Use of other software or customized register settings may effect actual power consumption. Maximum slide speed limit is widely selectable. For specification purposes, 40 and 20 cm/sec were selected as typical options.

Substantial power savings in suspend can be yielded if the system can provide a 12MHz (or 6MHz) clock input to the sensor. Crystal/Resonator power can be up to 25% or more of the suspended current drain.

3 Packaging and Pinout Information

3.1 Sensor Packaging

The AES1610 sensor is housed in a plastic molded 40 Ball Grid Array package using leadfree solder balls. The eXtendaBall thick package (designator code "DF") and the eXtendaBall thin package (designator code "FF") are shown below.



40 BGA eXtendaBall Thick Package



40 BGA eXtendaBall Thin Package

3.2 Recommended PCB Footprint

The PCB BGA pad sizes for the AES1610 which uses 0.60mm BGA balls, as shown on the package drawing, shall be 0.50 mm round pads with a 0.50 mm square solder mask and solder paste opening. The use of a >0.50 mm circular solder mask is authorized, but the square shape is preferred.

3.3 Topside Pin A1 Identification

The AES1610 package is fully symmetrical and thus there are no notches or other markings to signify pin A1 location when viewed from the top.

You can ensure that the sensor is mounted correctly by observing the asymmetrical drive bars visible on the sensor surface. This drive ring provides the TruePrint signal to the finger but also enables Pin A1 to be identified easily. This asymmetry is compatible with most vision-based inspection and pick & place equipment.

Pin A1 is located in the top left corner of the package when the thicker drive bar is located at the bottom of the sensor.

| Pin A1in top left corner |
|---------------------------|
| Thin Drive Bar on Top |
| Thick Drive Bar on bottom |
| |
| |
| 2 1 |
| A |
| O O B |
| 0 O C |
| |

Backside Pin A1 is indicated by a single gold triangle in the corner of the package.

40 BGA eXtendaBall thick package mass: 0.20 grams 40 BGA eXtendaBall thin package mass: 0.10 grams



3.4 Pin List by Interface

Pin assignments and pin function descriptions for the AES1610 sensor are shown below. The following pin list matches AuthenTec's certified reference designs.

| Pin | Туре | Digital Activity | Signal Name |
|------------|----------|------------------|-------------|
| A1 | Input | Active | DRIVE_RING |
| A2 | Power | | VDDA |
| A3 | Reserved | | N/C |
| A4 | Ground | | VSS |
| A5 | Passive | Static | PLL_FILTER |
| A6 | Power | | VDDA |
| A7 | Input | Active | SF_MISO |
| A 8 | Output | Active | GPO2 |
| A9 | Output | Active | GPO1 |
| A10 | Ground | | VSS |
| B1 | Ground | | VSS |
| B2 | Input | Active | SYS_CLK |
| B3 | Power | | VDD |
| B4 | Power | | VDD |
| B5 | Output | Active | VDDA_ON* |
| B6 | Power | | VDD |
| B7 | I/O | Active | DPLUS |
| B 8 | I/O | Active | DMINUS |
| B9 | Ground | | VSS |
| B10 | Output | Active | SF_MOSI |
| C1 | Input | Static | VSSL |
| C2 | Input | Static | SYSCLKSEL1 |
| C3 | Input | Static | SYSCLKSEL0 |
| C4 | Input | Static | VSSL |
| C5 | Output | Active | GPO0 |
| C6 | Output | Active | SF_CS* |
| C7 | Output | Active | ENUM |
| C8 | Output | Active | SF_WP* |
| C9 | Output | Active | SF_CLK |
| C10 | Ground | | VSS |
| D1 | Output | Active | FDRV |
| D2 | Power | | VDDA |
| D3 | Input | Active | RESET* |
| D4 | Ground | | VSS |
| D5 | Input | Active | DRIVE_RING |
| D6 | Passive | | OVC_SENSE |
| D7 | Power | | OVC_VDDA |
| D8 | Input | Static | VSSL |
| D9 | Output | Active | OVC_DET |
| D10 | Power | | |

Pin List by Interface

3.5 Pin Type and Activity Definitions

| VDD Power Supply Connections |
|--|
| VSS Power Supply Connections |
| Connections to passive components (ex: Filter caps, etc) |
| Active Inputs to the sensor |
| Active Outputs from the sensor |
| Active I/O's from the sensor (state / configuration dependent) |
| Do Not Connect anything to these pins |
| DC or slowly changing voltages |
| Active Signals, Digital or Analog |
| Fixed Active High Logic Level |
| Fixed Active Low Logic Level |
| Pixel Array Power supply pin |
| Pixel Array Ground supply pin |
| No Connection externally |
| |

3.6 Pin Descriptions (alphabetical listing)

| Pin(s) | Signal | Function Description | | | |
|------------|------------|--|--|--|--|
| Do | | Nagative helf of differential LISP signals | | | |
| | | Desitive half of differential USB signals | | | |
| | | Connection to the drive ring on the concer | | | |
| | | Connection to the drive ring on the sensor | | | |
| D5 | | Connection to the drive ring on the sensor | | | |
| 07 | ENUM | Enumerates sensor to USB nost by driving DPLS through a 1k resistor | | | |
| D1 | FDRV | TruePrint Signal Output used to drive TPRF signal though external circuitry to | | | |
| | 0.500 | the finger drive bezel and on-sensor drive ring | | | |
| C5 | GPO0 | General Purpose Output pins, used for debug or LED control | | | |
| A9 | GPO1 | General Purpose Output pins, used for debug or LED control | | | |
| A8 | GPO2 | General Purpose Output pins, used for debug or LED control | | | |
| D9 | OVC_DET | Over Current Detect Power Off output – Active low for power on. Refer to | | | |
| | | reference design schematics for detail. | | | |
| D6 | OVC_SENSE | Load side of current sense resistor input for over current control. Refer to | | | |
| | | reference design schematics for detail. | | | |
| D10 | OVC_VDD | Always-on power for Over Current protection circuit | | | |
| D7 | OVC_VDDA | Reference power supply rail for Over Current Protection circuit | | | |
| A5 | PLL_FILTER | Refer to USB Reference Design Schematic for appropriate filter components / | | | |
| | _ | connections | | | |
| A3 | Reserved | Reserved Pin – Do not connect | | | |
| D3 | RESET* | Sensor Reset Pin – Refer to Section 3.9 | | | |
| C9 | SF_CLK | SPI clock pin to external serial flash ROM device | | | |
| C6 | SF_CS* | SPI chip select to external serial flash ROM device | | | |
| B10 | SF_MOSI | SPI data input to external serial flash ROM device | | | |
| A7 | SF MISO | SPI data output from external serial flash ROM device | | | |
| C8 | SF_WP* | Write Protect input to external serial flash ROM device | | | |
| B2 | SYS CLK | System Clock Input – Refer to Section 3.7 | | | |
| C3 | SYSCLKSEL0 | Selects between available clock frequencies or external clock. Refer to | | | |
| | | section 3.7 | | | |
| C2 | SYSCLKSEL1 | Selects between available clock frequencies or external clock. Refer to | | | |
| | | section 3.7 | | | |
| B3,B4,B6 | VDD | Digital Power | | | |
| A2,A6,D2 | VDDA | Analog Power | | | |
| B5 | VDDA ON* | Controls power to analog circuitry. Used as FET gate input on VDDA | | | |
| A4,A10.B1. | VSS | Ground | | | |
| B9,C10,D4 | | | | | |
| C1.C4.D8 | VSSL | Logic Low Input | | | |

AES1610 Active Pin Functional Description

3.7 Clock Select Control

AES1610 supports clock sources of either 6MHz or 12MHz. The AES1610 uses a single pin crystal/resonator oscillator circuit that can also be overdriven with an external clock source capable of driving >+/-5mA.

Clock frequency selection [including clocks driven into the SYS_CLK pin (Pin B2) is done via the SYSCLKSEL[1:0] input pins. The following table shows the SYSCLKSEL[1:0] pin configurations:

| SYSCLKSEL[1:0] Pins C2:C3 | Crystal/Resonator or Clock Frequency Ranges |
|------------------------------|--|
| 00 | 6 MHz (nominal) |
| 01 | 12 MHz (nominal) |
| 10 | Reserved |
| 11 | Reserved |

SYSCLKSEL Decode

3.8 Low-Power Oscillator

The Low-Power Oscillator (LPO) is an internal oscillator circuit which produces a low frequency, low power clock signal for clocking sensor timers when suspended. This enables the sensor to turn off the higher frequency clock domains, the 12MHz oscillator, and the PLL. The LPO has a nominal frequency of 20KHz with a range from 10KHz to 40KHz. The AES1610 automatically determines the LPO frequency at power-up and continually while in suspend.

3.9 AES1610 Start-up

The RESET* pin is active low and has an internal pull-up resistor that is nominally 57K ohms with approximately 25% tolerance. This pin can generate a power-on reset for the sensor by adding a capacitor to ground. The capacitor must be selected so that the power on reset time constant is larger than the power supply ramp time plus the clock ramp time. Alternatively, though specifically not recommended, RESET* may be driven by the host directly, with the same requirement that it be held low during the power supply ramp time and the clock ramp time and only released after the allocated start-up time.

3.9.1 Crystal or Resonator Clocking

When a crystal or resonator is connected to the SYS_CLK pin, the clock start-up time is dependant upon the crystal or resonator. The load capacitance on SYS_CLK and the characteristics of the crystal or resonator will determine this start-up time. It is important to use the component values with similar crystal performance characteristics specified in the AuthenTec reference design. This is provided in documents which are part of the AuthenTec RDK.

AuthenTec's reference design, has an allocation for oscillator start-up time of 8.4ms. In this case, RESET* can be released a minimum of 8.4ms after Vdd reaches 3.0V.



Figure 3-1 Start-Up with Crystal or Resonator

When using Power On Reset controlled by capacitor RC control, the sensor RESET_n input RC time constant must be calculated. It is very important to determine the minimum time that the RESET_n will be held active, as the clock must have completed its startup when RESET_n goes inactive. The RC time constant begins from the moment of power is turned on. However, the Power On Reset time must be larger than the power supply ramp time plus the clock startup time. This is to prevent slow power supply ramp times from affecting proper clock startup timing.

For example, assume the maximum power supply ramp time to minimum operating voltage is 400 μ s and the clock startup time to 1 Vpp is 8 milliseconds maximum. Using a 0.22 μ F capacitor, at minimum value from the 10% tolerance, with the minimum possible internal pullup resistor value, yields the following minimum timing for RESET_n going inactive.

 $T_{min} = R_{min} * C_{min} = 42.8K * \sim 0.198\mu F = \sim 8.4 milliseconds.$

This equation can be used since the RESET_n threshold value is 70%VDD, roughly equivalent to one time constant.

One millisecond after reset is released the sensor will be ready for transactions. During this time the internal Phase Lock Loop will lock on the oscillator frequency.

4 Interface Descriptions

4.1 Interfaces

4.1.1 USB Interface

The USB interface of the AES1610 is USB2.0 Full Speed compliant. ESD recovery is employed that is designed to respond to loss of USB communication and latch-up events

The USB interface consists of the following pins:

| SIO/ Pin | Name | Direction | Description |
|----------|------|-----------|--|
| 0 / B7 | DPLS | I/O | Positive side of differential signaling |
| 1 / B8 | DMNS | I/O | Negative side of differential signalling |
| 2 / C7 | ENUM | 0 | Signals presence of sensor to USB host |

SIO Pin Definitions USB Interface



USB Interface

The USB descriptors for AES1610 are provided in the tables below.

| Field | Index | Value | Meaning |
|--------------------|-------|----------|--|
| bLength | 0 | 12h | Length of this descriptor = 18 bytes |
| bDescriptorType | 1 | 01h | Descriptor Type = Device |
| bcdUSB(L) | 2 | 10h | USB spec. version 1.10 (L) |
| bcdUSB(H) | 3 | 01h | USB spec. version 1.10 (H) |
| bDeviceClass | 4 | FFh | Device class (FF is vendor specific) |
| bDeviceSubClass | 5 | FFh | Device sub-class (FF is vendor specific) |
| bDeviceProtocol | 6 | FFh | Device Protocol (FF is vendor specific) |
| bMaxPacketSize0 | 7 | 08h | Max Packet size for EP0 = 8 bytes |
| idVendor(L) | 8 | FFh | Vendor ID (L) |
| idVendor(H) | 9 | 08h | Vendor ID (H) |
| idProduct(L) | 10 | 00h | Product ID low byte |
| idProduct(H) | 11 | 16h | Product ID high byte |
| bcdDevice(L) | 12 | Chip ID | Device ID (L) |
| bcdDevice(H) | 13 | Mask Rev | Device ID (H) |
| iManufacturer | 14 | 00h | None |
| iProduct | 15 | 01h | Product String – "Fingerprint Sensor" |
| iSerialNumber | 16 | 00h | None |
| bNumConfigurations | 17 | 01h | One configuration in this interface |

Device Descriptor

| Field | Index | Value | Meaning |
|---------------------|-------|-------|---|
| bLength | 0 | 09h | Length of this descriptor = 9 bytes |
| bDescriptorType | 1 | 02h | Type = Configuration |
| wTotalLength(L) | 2 | 20h | Total Length(L) including Interface and Endpoint descriptors |
| wTotalLength(H) | 3 | 00h | |
| bNumInterfaces | 4 | 01h | Number of interfaces in this configuration |
| bConfigurationValue | 5 | 01h | Configuration value used by Set Configuration to select this interface |
| iConfiguration | 6 | 00h | 00h = no string reference |
| bmAttributes | 7 | A0h | A0h, Attributes: bus-powered, remote wake- |
| | | | up supported |
| MaxPower | 8 | 32h | Max current =100mA |

Default Configuration Descriptor

| Field | Index | Value | Meaning |
|--------------------|-------|-------|--|
| bLength | 0 | 09h | Length of the Interface descriptor = 9 bytes |
| bDescriptorType | 1 | 04h | Descriptor type = interface |
| bInterfaceNumber | 2 | 00h | Zero based index of this interface = 0 |
| bAlternateSetting | 3 | 00h | Alternate setting =0 |
| bNumEndpoints | 4 | 02h | Number of endpoints in this interface (not |
| | | | counting enapoint() |
| bInterfaceClass | 5 | FFh | Interface Class = vendor specific |
| bInterfaceSubClass | 6 | FFh | Interface Sub Class = vendor specific |
| bInterfaceProtocol | 7 | FFh | Interface Protocol = vendor specific |
| iInterface | 8 | 00h | Index to string descriptor = none |

Default Interface 0, Alternate Setting 0 Descriptor

| Field | | | |
|-------------------|-------|-------|----------------------------------|
| | Index | Value | Meaning |
| | 0 | 07h | Descriptor length = 7 bytes long |
| bLength | | | |
| bDescriptorType | 1 | 05h | ENDPOINT descriptor |
| bEndpointAddress | 2 | 81h | In endpoint, endpoint #1 |
| bmAttributes | 3 | 02 | xfr type = Bulk |
| wMaxPacketSize(L) | 4 | 20h | Max Packet Size = 32 bytes |
| wMaxPacketSize(H) | 5 | 00h | |
| bInterval | 6 | 00h | Polling interval in milliseconds |
| Field | | Value | Meaning |
| bLength | 0 | 07h | Descriptor length = 7 bytes long |
| bDescriptorType | 1 | 05h | ENDPOINT descriptor |
| bEndpointAddress | 2 | 02h | Out endpoint, endpoint #2 |
| bmAttributes | 3 | 02h | xfr type = Bulk |
| wMaxPacketSize(L) | 4 | 08h | Max Packet Size = 8 bytes |
| wMaxPacketSize(H) | 5 | 00h | |
| bInterval | 6 | 00h | Polling interval in milliseconds |

Default Interface 0, Alternate Setting 0, Bulk Endpoint Descriptors

| Field | Index | Value | Meaning |
|-----------------|-------|-------|-----------------------------|
| bLength | 0 | 04h | String Index 0 |
| bDescriptorType | 1 | 03h | String descriptor type |
| wLANGID(0)(L) | 2 | 09h | Language ID for English (L) |
| wLANGID(1)(H) | 3 | 04h | Language ID for English (H) |

String 0 Descriptor

| Field | Index | Value | Meaning |
|-----------------|-------|-------|---|
| bLength | 0 | 26h | String Index 1 |
| bDescriptorType | 1 | 03h | String descriptor type |
| bString | 2 | 4600h | "Fingerprint Sensor" – in UNICODE format "F" |
| | 4 | 6900h | "i", 00 |
| | 6 | 6E00h | "n", 00 |
| | 8 | 6700h | "g", 00 |
| | 10 | 6500h | "e", 00 |
| | 12 | 7200h | "r", 00 |
| | 14 | 7000h | "p", 00 |
| | 16 | 7200h | "r", 00 |
| | 18 | 6900h | "i", 00 |
| | 20 | 6E00h | "n", 00 |
| | 22 | 7400h | "t", 00 |
| | 24 | 2000h | " ", 00 |
| | 26 | 5300h | "S", 00 |
| | 28 | 6500h | "e", 00 |
| | 30 | 6E00h | "n", 00 |
| | 32 | 7300h | "s", 00 |
| | 34 | 6F00h | "o", 00 |
| | 36 | 7200h | "r", 00 |

String 1 Descriptor

4.1.2 Serial Flash Interface

The Serial Flash Interface on AES1610 provides a means of attaching a flash device to the sensor for access by the host through the sensor's USB interface. The ROM is intended to facilitate pre-boot authentication applications. The Serial Flash ROM Interface of the AES1610 follows standard 4-pin SPI protocol. There is a fifth pin commonly used as "Write Protect" on standard flash parts. This pin is typically used to protect the flash device from being written to. This is particularly useful when the host is issuing commands to determine what type of flash is connected to the AES1610, as one flash's READ_ID command may be another's ERASE command.

The AES1610 acts as a pass-through for communication from the host to the serial ROM device. For communication from the serial flash device to the host, the AES1610 is programmed to fetch a certain number of bytes from the flash and send those bytes to the host. The AES1610 utilizes its 512 byte frame buffer to create large transfers from the flash, to the host. The AES1610 can also be programmed to sign data from the flash device using the same authentication mechanisms available for signing image data.

AuthenTec maintains a list of certified suppliers of the serial flash which the AuthenTec software will work with. Consult AuthenTec applications, sales, or your local representative to get the latest information.

4.1.3 General Purpose Outputs

The AES1610 has three General Purpose Output pins, GPO[2:0]. The GPO[2} pin is defaulted to output the status of the internal USB_SUSPEND signal. The GPO[1] pin is defaulted to output the status of the internal USB_OE* signal. These defaults are provided as a means of sensor debug as well as useful status to the host if desired. GPO[0] has no default setting, therefore during sensor debug it will remain on its selected signal though a RESET* assertion. The host should take care to program GPO[0] to a valid selection prior to entering a low-power state.

The three GPO pins can be utilized by the system to provide either sensor status or drive LEDs.

5 Data Formats

5.1 Overview

The sensor communicates with the host via data packets. A data packet is considered a set of messages returned by the sensor in response to a command. The data packet includes an image data message, histogram message, authentication message, and a register message. Each message is preceded by a 1-byte message header for data synchronization. Note that since the pixel data formats use all 8-bits per byte, the header bytes are not unique in the data stream.

5.2 Image Data Message Format

The image data formats use all 8-bits per byte. The header for the frame is sent first, followed by each column vector sent as binary packed (1-byte), gray scale 2-bit per pixel (2-bytes), or gray scale 4-bit per pixel (4-bytes) image data message formats.

5.3 Histogram Message Format

When the histogram message is enabled, the histogram is returned once per image. The histogram message is preceded by a header byte. The header is followed by the counts for each of the bins representing possible pixel values. Bin 0 (the number of pixels whose value is 0) is sent first. This is followed by the counts for the remaining bins. The maximum value in any bin will be 128.

5.4 Authentication Message Format

The authentication word is sent after an image is complete. The authentication word message is preceded by a header byte. The authentication word is used to validate that the transaction is authentic (i.e. that the image data isn't merely being provided from some storage device containing a valid fingerprint image).

5.5 Registers Message Format

When a request to read registers is received, all of the register values are returned preceded by the address for that register. Unused or reserved register bits are always read as 0. Registers are written to by writing the register address followed by the data byte.

5.6 Flash ROM Data Format

When data is read from the flash, the AES1610 will prefix the data with a two-byte header.

6 Image Acquisition

The sensor array is composed of 128 x 8 pixels. The sensor communicates with the host processor via data packets. A data packet is a set of messages returned by the sensor in response to a command. The data packet includes an image data message, histogram message, authentication message, and a register message. Each message is preceded by a 1-byte message header for data synchronization.

7 Navigation

For accurate cursor placement, the AES1610 has implemented an on-chip navigation timing engine. By accurately timing a set of captured images, accurate dx/dy motions can be calculated over a broad range of finger motions. The dx/dy calculations are performed in software. When the sensor is in navigation mode, the sensor returns very small navigation data packets to the host for processing. The AES1610 supports menu scrolling, single and double taps, multi-finger speed dialing, and gaming quality navigation.

8 Power Management

Two methods exist for further reducing power consumption and extending battery life.

- Using the externally driven clock. Please refer to section 3.5.
- Reducing the swipe speed. Swipe speed is variable in software from 20cm/s 30cm/s. Please refer to table 2.3.

9 Part Numbering Scheme

AES1610 - I - PP - CC - DDEE : 3.0 - 3.6V I/O

I = Temperature Range

C = Commercial temperature range = 0C to 70C

*Note: All package balls are lead-free.

<u>PP = Packaging Options</u> DF = 40 BGA Thick (1.96mm) eXtendaBall package FF = 40 BGA Thin (1.34mm) eXtendaBall package

<u>CC = Carrier Options</u> CA = Plastic Carrier Trays with 245 sensors per tray TR = Tape & Reel w/ 3000 sensors per reel (thick package) and 3500 sensors per reel (thin package) SB = 10 unit sample pack (thick gold only)

DD = Drive Ring Options: GO = Gold NI = Nickel

<u>EE = Options</u> 00 = Silicon revision code in 1610 series*

* Contact AuthenTec Sales for current revision code.

Example: AES1610 with Thick eXtendaBall BGA package, Gold ring, shipped as tape reels: AES1610-C-DF-TR-GO00

10 Hazardous Material Compliance

The AuthenTec AES1610 is manufactured to be in compliance with various world wide standards specifying the elimination of hazardous substances.

The silicon IC as well as the physical packaging and associated bezel are Lead (Pb) free and do not contain any of the hazardous substances currently being eliminated within the semiconductor industry.

The AES1610 is EU RoHS compliant.

11 Revision History

| Version | Date | Person | Reason |
|---------|----------|--------|---|
| 1.0 | 12/20/05 | Hicks | Preliminary Specification |
| 1.1 | 02/10/06 | Hicks | Modified section 3.8 to specify a range for load |
| | | | capacitance. |
| 1.2 | 03/23/06 | Hicks | Removed the thin package |
| 1.3 | 04/12/06 | Lee | Added PinA1, Text Updates, Formatting |
| 1.4 | 05/22/06 | Hicks | Added eXtendaBall packages and product mass, |
| | | | corrected the number of units/tray |
| 1.5 | 06/05/06 | Hicks | Updated the 40 BGA eXtendaBall drawing, added the |
| | | | backside laser part marking |
| 1.6 | 07/10/06 | Hicks | Added recommended PCB footprint, changed the |
| | | | navigation current consumption |
| 1.7 | 02/09/07 | Hicks | Corrected the "SB" carrier option, removed * from the |
| | | | OVC_DET signal, removed the standard package, |
| | | | modified the clock startup section |

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EntréPad AES1610 Slide Sensor Data Sheet

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